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## Overview:

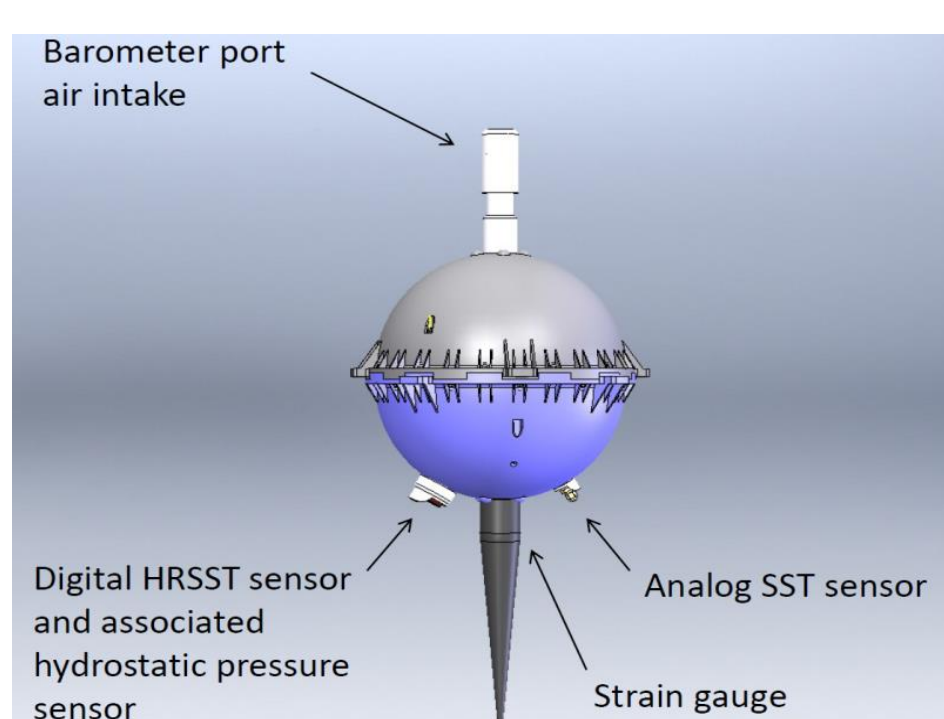
- New radiometer the 'Sea and Land Surface Temperature Radiometer' (SLSTR) on Copernicus Sentinel-3 A/B require high quality Fiducial Reference Measurement (FRM) data for calibration and validation purposes.
- New Copernicus-funded drifting buoy design to include a high accuracy and high frequency (1Hz) sampling capacity, with additional digital probe and near-surface water pressure sensor.
- FRM measurements to be linked to SI traceability, and include documentation of the SST accuracy / uncertainties and metadata.
- New design complies with DBCP SVP standards, with a new array of 100+ buoys planned.
- 2 Phase to project: Design and Validation, Production and Deployment
- Deployment plan focused on sensitive areas
- Data available on public repository (Drifting Buoy Global Data Assembly Center, GDAC, hosted by Ifremer)
- 6 Partners: CLS, nke instrumentation, Meteo-France, SHOM, BSH, JCOMMOPS.
- Project to run until the end of 2021.



The Sentinel-3 Satellite

## Design & Assembly:

- Based on nke instrumentation SVP-40 drifter
- Sensor array:
  - Analog Temperature sensor
  - Strain Gauge
  - Vaisala PTB110 Barometer
  - HR Temperature & hydrostatic pressure sensor



Schematic of the SVP-BRST Buoy

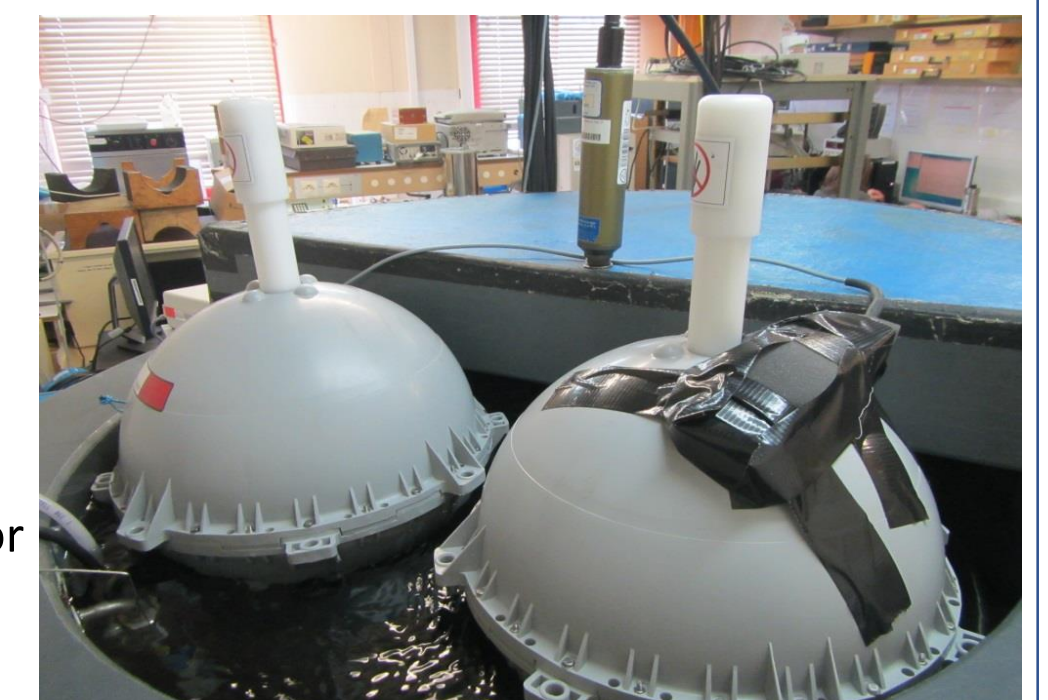


1<sup>st</sup> Production Batch in NKE Offices

- Iridium 9602 transceiver with Maxtena antenna for communication
- GNSS module with positioning error
- 2 alkaline batteries provide power for at least 18 months
- Sensors initial calibration in nke testing facility
- User set up through PC with Bluetooth
- 2 prototypes tested and deployed in Mediterranean sea from April 2018 to January 2019
- Design Validated and production phase initiated
- 2 message format to transmit data to GTS (91 and 92)

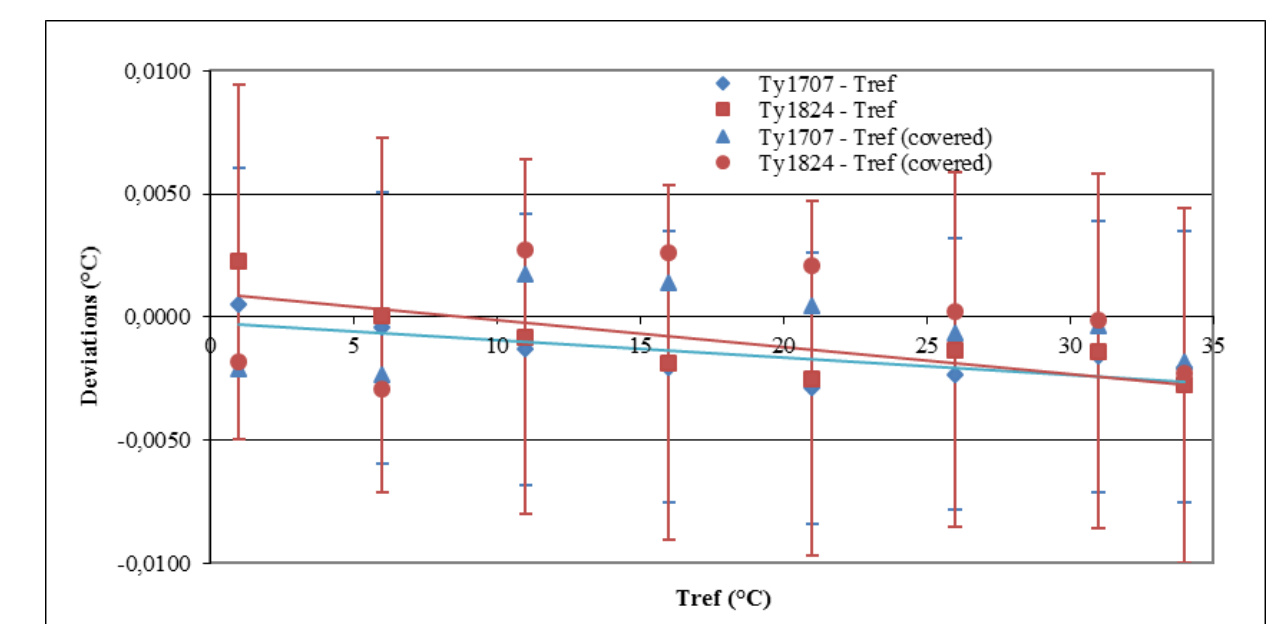
## Metrology:

- Performed by the SHOM
- Dual Step approach:
  - calibration of temperature sensors
  - verification of sensors within the buoy
- High Resolution Sensor and Analog Sensor calibrated with SBE35 reference thermometer regularly checked in triple point of water and fusion point of gallium cells
- Response time of HRSST sensor also measured in bath with SI linked instruments
- Range from 1°C to 35°C,
- Verification at sea by comparison to an SBE35 fixed to an MBSA



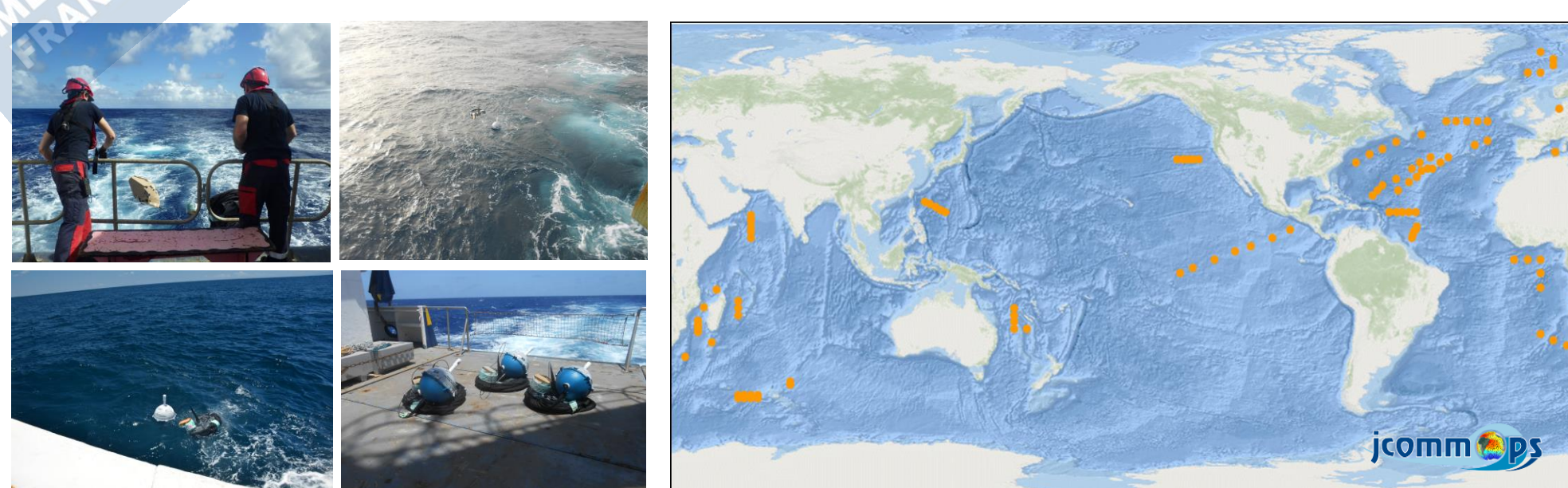
The 2 prototypes in the Metrology Lab

- Expanded uncertainty:
  - -HRSST sensor: 5 to 7mk
  - -SST sensor: 12 to 14mk
- Prototypes tests confirm that metrology approach
- For each batch of 50 buoys,
- All sensors calibrated
- And 5 Buoys verified.



The 2 prototypes HRSST calibration curve

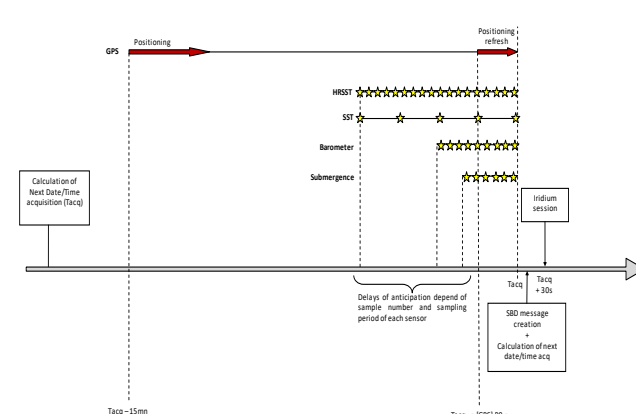
## Deployment:



Photos of first Deployments

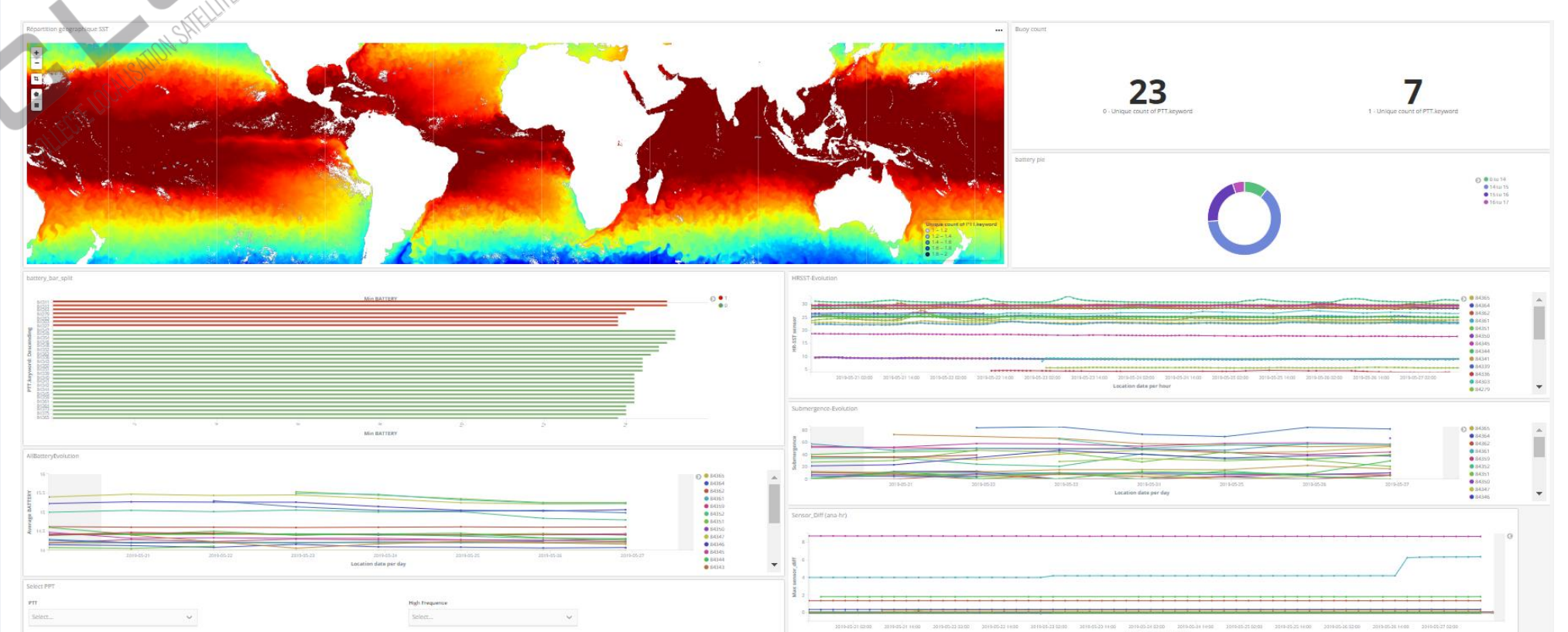
Map of deployment Plan (from Jcommops Website)

- First Batch of 50 buoy delivered by nke instrumentation on 04/12/2018
- Deployment plan coordinated by Meteo-France
- Deployment plan and metadata on JCOMMOPS website
- Second batch due to be received 12/06/2019
- Combination of High Frequency and low Frequency buoys
  - LF: 1 Message per hour, Mean and Percentile
  - HF: 5 Message per hours, 300 Temperature data points



Sampling Strategy

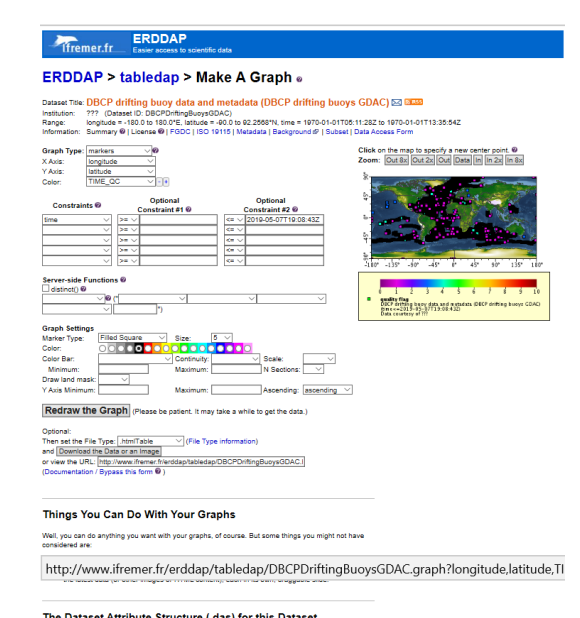
## Monitoring and Data access:



Monitoring Portal with Battery and sensor data refreshed in real time

- Raw data Via FTP (credential required)
- csv file available via argosweb portal
- Netcdf (cf compliant) on the Coriolis GDAC portal:

- FTP: <ftp://ftp.ifremer.fr/ifremer/dbcp-drifter/gdac/active/>
- ERDDAP: <http://www.ifremer.fr/erddap/tabledap/DBCPriftingBuoysGDAC.graph>



## References:

Poli, P., Lucas, M., O'Carroll, A., Le Menn, M., David, A., Corlett, G. K., Blouch, P., Meldrum, D., Merchant, C. J., Belbeoch, M., and Herklotz, K.: The Copernicus Surface Velocity Platform drifter with Barometer and Reference Sensor for Temperature (SVP-BRST): genesis, design, and initial results, Ocean Sci., 15, 199-214, <https://doi.org/10.5194/os-15-199-2019>, 2019.

Sybrandy, A. L., Niiler, P.P., Martin, C., Scuba, W., Charpentier, E., Meldrum, D.T.: Global Drifter Programme Barometer Drifter Design Reference, DBCP Rep. 4, rev. 2.2, 2009.